# ZERO EMISSION VEHICLES AUSTRALIA



http://www.zeva.com.au



# EVMS Lite v2.0

#### Introduction

Thank you for purchasing ZEVA's Electric Vehicle Management System. The EVMS was developed to address the need for safer, more reliable and better integrated EV conversions. The Lite module is a simplified version of our EVMS Core, for those with simpler functional requirements, and some features more suited to stationary and off-grid power applications. The Lite communicates with battery management modules over CAN bus and manages drive/ load and charge circuits according to battery status, automatically shutting down outputs if any cells exceed safe voltage range.

It also features auxiliary contactor control (for managing any mid-pack contactors), remote LED for viewing status from the cabin and a buzzer output for audible warnings of any errors. The EVMS Lite can optionally be used with an EVMS Monitor module for viewing current vehicle status as well as full BMS information such as individual cell voltages and pack statistics. The Monitor may also be used for reprogramming BMS parameters over the CAN bus.

This manual describes the installation and operation of the EVMS Lite, with some additional content describing interaction with the EVMS Monitor.

# Safety Warning

Electric vehicles are high powered devices which involve potentially lethal voltages and currents. Proper precautions and electrical safety procedures should always be observed, voltages above 110VDC should be considered dangerous, and vehicles should never be worked on while power contactor(s) are engaged. Please read this manual carefully to ensure correct installation and operation. If you are unsure of anything, please contact us before proceeding.

We have endeavoured to make a safe and reliable product which performs as described, however since ZEVA has no control over the integration of its products into a vehicle, we can assume no responsibility for the final safety or functionality of the completed vehicle.

It is up to the end user to determine the suitability of the products for the purpose employed, and the end user assumes all risks associated. Products should only be installed by suitably qualified and experienced persons, and should always be used in a safe and lawful manner.

# Specifications

- Power supply: 12-14V nominal (8-20V maximum)
- Current consumption: 5mA idle, 25mA active
- Contactor outputs rated at up to 5A
- Dual CAN bus ports (5-pin Molex KK)
- Optional shunt interface (100A/200A/500A 75mV)
- Dimensions: 104x62x12mm
- Weight: 50g

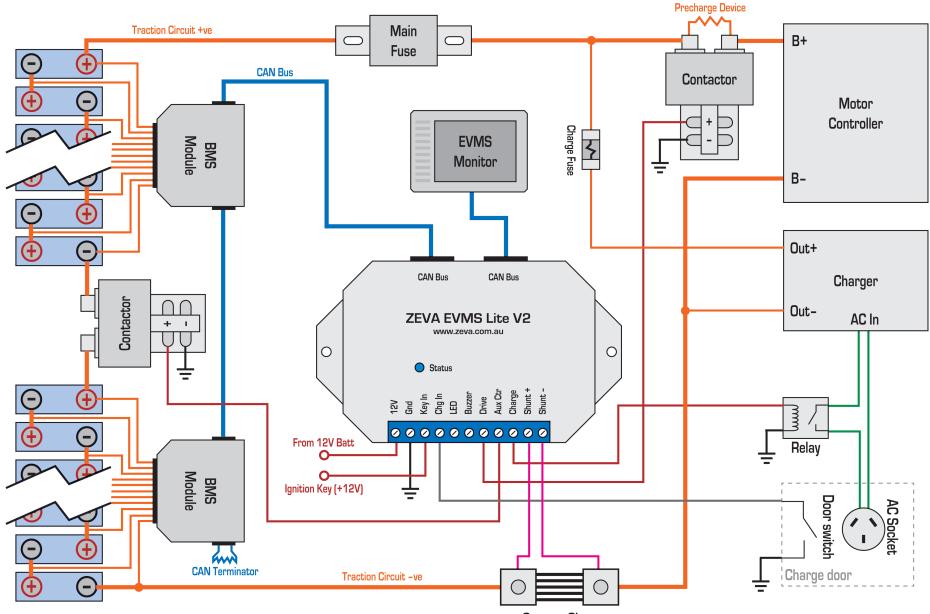
# **EVMS Lite Installation**

The EVMS Lite should be mounted securely in the vehicle with screws through the holes in the case, preferably in a location protected from the weather. The Lite has 11 screw terminals for its main connections, plus two CAN ports the opposite side. Wire gauge for most I/O connections should be around 18-20AWG to ensure reasonable mechanical strength and current rating.

The following page shows a typical wiring diagram for an EVMS Lite in a vehicle (plus associated BMS modules and EVMS Monitor).

### Wiring Diagram

The diagram below shows typical wiring for an EVMS Lite installation. Note that the diagram does not show a main fuse (5A recommended) and inertia switch (crash sensor), which should both be installed between the 12V battery and the EVMS Lite's 12V supply. The LED output supplies up to 5mA for powering a remote status LED, and Buzzer outputs 12V whenever an error is present – both typically used only when there is no EVMS Monitor. Make sure all wiring has appropriate current and insulation ratings, and that fuses have appropriate DC voltage and current ratings.



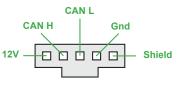
**Current Shunt** 

#### **Description of EVMS Lite connections**

Terminal name	I/O	Description
12V	Input	To 12V battery positive (permanent supply, not key switched). Approx 9-18V maximum range.
Ground	Input	To vehicle chassis, or 12V battery negative.
Key in	Input	To key signal, should be +12V when key is turned on
Charge In	Input	Connect to your charge detection switch, such as a fuel door switch or 240V detect relay/circuit. Should pull to ground when the switch is on (so attach other side of switch to chassis, near the switch is fine).
LED	Output	Allows for wiring of a remote LED for viewing status in cabin. 5mA limited. Connect this pin to LED anode, and cathode to ground/chassis.
Buzzer	Output	Connect a 12V piezo buzzer to this output pin for an audible warning when errors are detected.
Drive	Output	Supplies 12V to the main contactor, precharge system or motor controller while the key is on and the BMS reports no errors.
Aux Ctr	Output	Supplies 12V to any auxiliary contactors you may have such as pack break-up contactors, while either driving or charging.
Charge	Output	Supplies 12V to a relay controlling power to the charger.
Shunt + Shunt –	Inputs	Two wires go to a current shunt, used for calculating power consumption and battery state of charge.

# **CAN Bus Wiring**

The EVMS Lite also has two CAN bus ports (5-pin Molex C-Grid SL) on one side of the case. These are wired identically, and can be connected in either order in any location along the CAN bus. (The EVMS Monitor and BMS12 modules use the same 5-pin plugs and wiring.)



CAN plug wiring as viewed on Monitor case

CAN buses work best when wired as a single daisy chain of devices, with 1200hm termination resistors across CAN H and CAN L wires at each end to prevent signal reflection. For this reason the EVMS Lite has two CAN ports, allowing installation anywhere in a daisy chain.

The order of devices is unimportant - usually the shortest path between devices is best.

The EVMS Monitor is most commonly installed at one end of the CAN bus so only has a single CAN port, and a built-in internal termination resistor. The monitor may be installed in the middle of a CAN bus by creating a short Y-branch off the bus to the Monitor's CAN plug, and removing the small pin jumper beside the plug to disable the internal termination resistor.

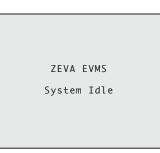
For the sake of noise immunity, CAN buses typically use twisted pair cable. Since electric vehicles can involve high electromagnetic interference (EMI) from the traction circuit, we recommend using shielded twisted pair (STP) wire for maximum noise immunity. Very short connections are usually OK with untwisted and/or unshielded cable.

#### **Current Shunt**

The EVMS Lite optionally uses a current shunt to measure current flow in the traction circuit, which allows it to calculate battery state-of-charge. The shunt measurement electronics are galvanically isolated from the rest of the device, so the shunt may be installed anywhere in the traction circuit (e.g battery positive or negative side) – but do ensure that all loads in/ out of the battery flow through the shunt. Positive current values displayed on the Monitor indicate discharge current, and negative values indicate charge current. If your values are reversed, simply swap the wires at the Shunt + and – temrinals on the EVMS. Twisting the pair of wires between the EVMS and shunt can help improve noise immunity.

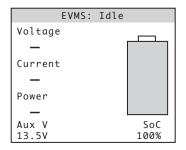
#### **EVMS Monitor**

The EVMS Monitor is a 3.2" colour touchscreen, used to remotely interact with other devices on the CAN bus, both for viewing operating data and to edit settings. The Monitor has various different pages of information as described below.



The default display when the vehicle is idle (neither driving nor charging), for systems without a current shunt.

In order to minimise quiescent power consumption while the vehicle is not in use, the EVMS Lite will power down the CAN bus after 1 minute in idle state. You can use this time window to enter Options and Settings modes.



EVMS:	Running
Voltage 148V	
Current 42A	
Power 6.2kW	
Aux V	SoC
13.5V	90%

EVMS: Running Pack voltage Avg temp 149.4V 23°C Min voltage Max voltage 3.31V 3.33V M0 C4 M2 C8

BMS Detail	s: Module 1
Cell voltage	es
3.32V 3.33V 3.33V 3.31V 3.31V 3.32V	3.32V 3.32V
Temp1: 23°C	Temp2: 25°C
Prev	Next

The default display when the vehicle is idle (neither driving nor charging), for systems with a current shunt and hence able to calculate State of Charge, Current and Power. Battery state of charge and auxiliary battery voltage are visible, but other parameters are only available while driving or charging.

The standard display when Running or Charging, showing instantaneous voltage, current, power, auxiliary battery voltage and traction battery State of Charge.

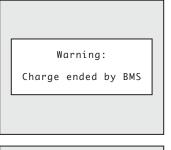
Touching the left or right half of the display will swap to the previous or next display page respectively.

BMS summary page, showing the pack voltage, average temperature, and the voltage and location of both the lowest and highest cells.

Along the bottom is a bar graph showing all cells being monitored. Green bars indicate cells within range. Bars will change to blue for undervoltage cells, orange for cells being balanced, and red for overvoltage cells.

Detailed information for a single BMS module, showing voltage of each cell (to 2 decimal places) and two temperatures if available. Orange bars beneath the voltages indicate if cell shunts are currently on.

Touch within the Prev and Next buttons to change which BMS module is being viewed, or anywhere else in the display to change Monitor pages.



Reset SoC	
Enter Setup	
Display Off	
Exit Options	

If the EVMS detects an error, this warning page will be displayed. In most cases, the error can be acknowledged/reset by pressing Select. For a full list of errors you might see, refer to section *Error Detection*.

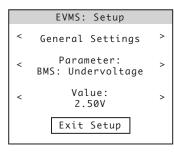
You can bring up this options menu by holding your finger down for 1 second. From here you can enter the Setup mode, or switch the display off. (Note that Reset SoC only works with EVMS Core.)

When the display is off, touch and hold anywhere for 1 second to turn it back on. Display will automatically wake if there is a new warning to display.

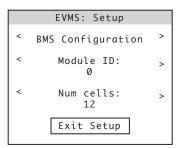
Setup mode can only be entered from Idle state, i.e when the vehicle is not charging or being driven.

# **Configuring Settings**

The EVMS Monitor can be used to configure settings for all devices on the CAN bus. (Note: A stylus or similar pointy object can be used if you find your finger isn't accurate enough!)



The Setup mode has three rows. The top row toggles between the General Settings and the Pack Configuration sections. Tap the arrows either side to nagivate between these. In the General Settings page, the second row selects the parameter to be modified, and the third row modifies the parameter itself. The Exit Setup button will distribute new settings to all devices on the network then return to normal operation.



This is the page for configuring your battery pack, so the BMS knows how many cells to monitor.

Tap the arrows either side of the Module ID row to select the module in question, and the arrows either side of Num cells is used to modify how many cells that BMS module should expect.

### List of settings - EVMS Lite

The following table describes the parameters available in the General Settings page.

Name	Range	Description
Pack capacity	10-1000Ah	The rated capacity of your traction battery pack, in Amp Hours. For lead acids, use the C20 rate (see also section on Peukert's Effect).
SoC warning	0-99%	The EVMS can raise a warning when the traction battery's SoC reaches a predetermined level. Use 0% to disable.
Full voltage	1-400V	The EVMS uses a "full voltage" threshold combined with charge current dropping to under 2 amps to detect charge completion, and automatically reset the SoC to 100%.
Warn current	0-1200A	The EVMS will provide a warning if the current in the traction circuit exceeds this threshold.
Trip current	0-1200A	The EVMS will provide a warning and automatically shut down the traction circuit if current exceeds this threshold.
Min aux voltage	10-14V	If the vehicle's 12V supply drops below this threshold for more than 5 seconds, a warning will be provided. It may indicate a weak 12V battery and/or faulty DC/DC converter.
BMS: Min voltage	0 – 5.00V	Adjusts the low voltage warning threshold for each cell in your traction pack.
BMS: Max voltage	0 – 5.00V	Adjusts the high voltage warning threshold for each cell in your traction pack.

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BMS: Shunt voltage	3.00 - 5.00V	Adjusts the voltage at which shunt balancers turn on for each cell in the tracion pack.
BMS: Low temp warn BMS: Overtemp warn	-20 – 100°C -20 – 100°C	The EVMS can provide a warning if any BMS modules report a temperature below or above these respective thresholds. In Charging mode, where the vehicle is usually unattended, the EVMS automatically shuts the system down. In Running mode, only a warning is provided and the user must decide the appropriate action.
Stationary Mode	YES/NO	Switches the EVMS into Stationary Mode, for battery backup and off-grid power type applications. Please refer to "Stationary Applications" Section for more information.
Current sensor	None, 100A, 200A, 500A	Select the current shunt size as shipped with your EVMS Lite.
Display brightness	0 – 100%	Adjusts the brightness of the LCD display's backlight.
Buzzer On	YES/NO	Selects whether the Monitor should sound the buzzer for alerts. (Safest to leave this on.)
Use Fahrenheit	YES/NO	Changes display of temperature units to Fahrenheit instead of Celcius.

#### **Error Detection**

The EVMS monitors a wide range of operating parameters for your electric vehicle and can notify you if any exceed their safe range or any faults are detected. In most cases, errors can be acknowledged/reset by pressing the Select button. Critical errors are responded to automatically (such as by shutting down the traction circuit due to a critically low cell), while others are at the driver's discretion to respond to (such as over-temperature warnings). The following table describes the errors you may encounter.

Error	Description
Low battery charge	The battery's State of Charge has reached the programmed warning threshold.
Overcurrent warning	If battery current exceeds the programmed threshold for more than 1 second, this warning will appear.

Overcurrent shutdown	As above, except the EVMS will also automatically shut down the traction circuit if this threshold is exceeded. Note that for safety reasons this system cannot replace a real fuse, though it can usually avoid blowing the real fuse.
BMS - low cell	A BMS module has reported a cell voltage below the minimum threshold.
Shutdown by BMS	A low cell condition has been present for more than 10 seconds, so the EVMS has shut down the traction circuit to protect the batteries.
BMS - high cell	A BMS module has reported a cell voltage above the minimum threshold.
Charge ended by BMS	A high cell condition has been present for more than 1 second, so the EVMS has shut down the charger to protect the batteries.
BMS - overtemp	A BMS module has reported a temperature above the programmed threshold.
BMS - undertemp	A BMS module has reported a temperature below the programmed threshold.
BMS - comms error	If the EVMS Lite hasn't received data from a BMS module for a while (about 1 second), this error will appear and the traction circuit will be shut down for safety.
Low 12V battery	The voltage of the 12V auxiliary battery (power supply for the EVMS) has dropped below the programmed threshold for more than 5 seconds. May indicate a weak battery or faulty DC/DC converter.

#### **Stationary Applications**

The EVMS configuration includes a setting for Stationary Mode, intended for use in battery backup and off-grid power applications, where charging and discharging may occur simultaneously. In this mode, the Key input enables both Main Contactor and Charge Enable outputs concurrently. An undervoltage cell will disable the Main Contactor output (to remove any loads on the battery) and an overvoltage cell will disable the Charge Enable output (to disable any charging sources). In both cases the outputs are re-enabled once the voltage has recovered by 0.4V (i.e there is  $\pm 0.2V$  hysteresis around the configured thresholds).

In Stationary Mode, the Charge Sense input is no longer used. The Aux Ctr output may be used to trigger low State-of-Charge warnings or charging systems (such as diesel generators), as it will output 12V whenever SoC is below the programmed threshold. Note that the output

will go off as soon as the SoC recovers above the threshold, so an external timer or latching device may be required to avoid rapid cycling.

For LiFePO4, we recommend an under-voltage threshold of 2.8V (which results in 2.6V cutout and 3.0V re-enabling for any loads on the battery), and an over-voltage threshold of 3.6V (for 3.8V charger cutout and 3.4V re-enabling). These thresholds give about 1% hysteresis on the battery state of charge to avoid rapid cycling of the charger or outputs.

#### **Tech notes**

• CAN bus power: CAN busses use a significant amount of power when operating, in the order of 20mA per node. In order to minimise quiescent power consumption (and avoid flattening your vehicle's 12V battery), the EVMS Lite powers down the CAN bus after 1 minute if the vehicle is neither driving or charging. As such, the BMS will no longer be monitoring your cells so it is of paramount importance that there are **no loads on the traction battery when the vehicle is idle**, or batteries could be damaged from over-discharge!

Once the CAN bus has powered down, you will be unable to enter Setup mode with a Monitor device. To remedy this, simply turn the key on and off, or turn the EVMS Lite off and on again, then enter Setup as normal within 1 minute.

• **Precharging your motor controller:** Motor controllers have a large input capacitor bank which must be precharged / soft started, to avoid a large inrush current when your contactor closes which can damage components. The EVMS Lite includes no controller precharge system, so you will need to arrange a precharge device for your motor controller if it does not have one built in. (Check out our Smart Precharger on the ZEVA website for more info.)

#### Tech support and warranty information

All ZEVA products are covered by a 12 month warranty against manufacturing faults or failures under normal operating conditions. The warranty does not cover misuse of the product, including but not limited to: excessive voltage or reversed polarity on terminals, short circuits on outputs, opening of housings and/or modification of internal electronics, severe impact damage (e.g due to vehicle crashes), submersion in water.

We have taken great care to design a safe and reliable product, but faults can happen. If you believe your product has a fault, please contact us via our website to discuss. If it is determined that a hardware fault is the likely cause, we will provide an RMA number and return address to proceed with repairs.

If you have any questions not covered by this manual, please contact us via our website:

http://www.zeva.com.au